

## Robotics Service Bus - Feature #635

### Implement not-origin filter

10/14/2011 11:02 PM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	10/14/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	100%
<b>Category:</b>	Python	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
Useful for avoiding self-notifications.			

#### Associated revisions

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##### Revision 0a3a2d90 - 10/15/2011 05:04 PM - J. Moringen

Added OriginFilter in rsb/filter.py

fixes #635

- rsb/filter.py: added class OriginFilter
- test/filtertest.py: added test suite OriginFilterTest

#### History

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##### #1 - 10/15/2011 05:10 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r2839.