

## Robotics Service Bus - Tasks #636

### Provide rst.JointAngles Testdata as rsbag logfile

10/15/2011 11:42 AM - S. Wrede

<b>Status:</b>	Resolved	<b>Start date:</b>	10/15/2011
<b>Priority:</b>	High	<b>Due date:</b>	
<b>Assignee:</b>	S. Wrede	<b>% Done:</b>	100%
<b>Category:</b>	Matlab	<b>Estimated time:</b>	0.25 hour
<b>Target version:</b>	0.5		
<b>Description</b>			
To allow easy testing of Matlab example.			

#### History

---

**#1 - 10/20/2011 03:07 AM - J. Moringen**

- Target version deleted (0.5)

**#2 - 10/20/2011 02:35 PM - S. Wrede**

- Status changed from New to Resolved

- Target version set to 0.5

- % Done changed from 0 to 100

Available since r2919. The test data was recorded in a simple example where a controller sends an 8-dimensional JointAngle vector to the Oncilla robot.