

## Robotics Systems Commons - Enhancement #654

### Improve cancellation of Tasks in the delay time

10/19/2011 06:32 PM - J. Wienke

<b>Status:</b>	New	<b>Start date:</b>	10/19/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	0%
<b>Category:</b>	Threading	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
<p>With the current cancellation system of tasks, waiting threads in waitDone can only be reliably notified about the cancellation when the run method is executed by the threaded executor. This costs time and also prevents further optimizations by the executor. Improve this so that:</p> <ul style="list-style-type: none"><li>- a cancel request before run is called immediately notifies waiting threads and prevents the task from running</li></ul>			

#### History

#1 - 06/30/2016 12:37 PM - J. Wienke

- Assignee deleted (J. Wienke)