

Robotics Service Bus - Feature #711

Implement socket-based transport

11/10/2011 02:38 AM - J. Moringen

Status:	Resolved	Start date:	11/10/2011
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Common Lisp	Estimated time:	0.00 hour
Target version:	rsb-0.7		
Description			
Related issues:			
Related to Robotics Service Bus - Enhancement # 545: Check if pure TCP Connec...		Resolved	09/05/2011
Related to Robotics Service Bus - Bug # 714: Bus-lock in socket-based transpo...		Resolved	11/10/2011

Associated revisions

Revision 816559ca - 12/14/2011 03:32 AM - J. Moringen

initial merge of changes from socket-transport branch fixes #714, refs #711

History

#1 - 11/11/2011 08:32 AM - J. Moringen

- Status changed from Resolved to In Progress
- % Done changed from 100 to 90

#2 - 02/16/2012 02:03 PM - J. Moringen

- Status changed from In Progress to Resolved
- % Done changed from 90 to 100

I can't remember what was missing here.

#3 - 08/16/2012 10:14 PM - J. Moringen

- Target version changed from rsb-1.0 to rsb-0.7