Robotics Service Bus - Tasks #715
Integrate socket-based transport into integration test

11/10/2011 01:00 PM - J. Moringen

Status:	Resolved		**Start date:**	11/10/2011
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:	Language Integration		**Estimated time:**	0.00 hour
Target version:	rsb-0.7			

Description

Related issues:

Related to Robotics Service Bus - Enhancement # 545: Check if pure TCP Connec...	**Resolved**	**09/05/2011**

Associated revisions

Revision 9446395b - 11/10/2011 01:31 PM - J. Moringen

Allow flexible transports in test/integrationtest.py

refs #715

- test/integrationtest.py: added transport parameter to generation of
  test case method which involved network communication; allow passing
  additional environment variables to child processes; generate
  additional configuration depending on the selected transport; added
  commandline option for specifying transports to test

Revision f036eaaf - 11/10/2011 08:47 PM - J. Moringen

Removed limitations to Spread transport from Lisp programs

refs #715

- lisp/common.lisp: removed spread: scheme from URI; load usocket to
  make socket-based transport available, if possible
- lisp/informer.lisp: likewise
- lisp/listener.lisp: likewise

History

#1 - 11/16/2011 02:59 AM - J. Moringen

- % Done changed from 0 to 70

#2 - 06/27/2012 03:10 AM - J. Moringen

- Status changed from In Progress to Resolved

- Target version changed from rsb-1.0 to rsb-0.7

- % Done changed from 70 to 100

Tests for all languages are implemented and enabled. May still fail at the moment, however.