

## Robotics Service Bus - Feature #726

### Implement Connector Subsystem in Java

11/18/2011 03:13 PM - S. Wrede

<b>Status:</b>	Resolved	<b>Start date:</b>	11/18/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Java	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.9		
<b>Description</b>			
Subtasks:			
<ul style="list-style-type: none"><li>- Check that Connector interfaces exist and In/Out Connectors are supported</li><li>- Connector instances must be created through a Factory</li><li>- Dynamic registration of Connector types should be supported</li><li>- Spread transport must be adapted</li><li>- Implement local transport as additional test case</li></ul>			
<b>Related issues:</b>			
Blocks Robotics Service Bus - Tasks # 325: Implement Local Transport			<b>Resolved</b> <b>05/26/2011</b>

#### History

##### #1 - 02/27/2012 03:31 PM - J. Wienke

- Target version deleted (0.6)

##### #2 - 11/06/2012 12:40 AM - J. Moringen

- Status changed from New to In Progress

- Assignee changed from S. Wrede to J. Moringen

- % Done changed from 0 to 20

##### #3 - 08/19/2013 08:25 AM - J. Wienke

- Status changed from In Progress to Resolved

- Assignee changed from J. Moringen to J. Wienke

- Target version set to rsb-0.9

- % Done changed from 20 to 100

This has been solved while implementing #713.