

Robotics Service Bus - Feature #726

Implement Connector Subsystem in Java

11/18/2011 03:13 PM - S. Wrede

Status:	Resolved	Start date:	11/18/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Java	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
Subtasks:			
<ul style="list-style-type: none">- Check that Connector interfaces exist and In/Out Connectors are supported- Connector instances must be created through a Factory- Dynamic registration of Connector types should be supported- Spread transport must be adapted- Implement local transport as additional test case			
Related issues:			
Blocks Robotics Service Bus - Tasks # 325: Implement Local Transport			Resolved 05/26/2011

History

#1 - 02/27/2012 03:31 PM - J. Wienke

- Target version deleted (0.6)

#2 - 11/06/2012 12:40 AM - J. Moringen

- Status changed from New to In Progress
- Assignee changed from S. Wrede to J. Moringen
- % Done changed from 0 to 20

#3 - 08/19/2013 08:25 AM - J. Wienke

- Status changed from In Progress to Resolved
- Assignee changed from J. Moringen to J. Wienke
- Target version set to rsb-0.9
- % Done changed from 20 to 100

This has been solved while implementing #713.