

Robotics Service Bus - Feature #759

Check RSB Real-Time compatibility

12/09/2011 06:17 PM - Anonymous

Status:	Closed	Start date:	12/09/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	20%
Category:	C++	Estimated time:	0.00 hour
Target version:			

Description

First experiments didn't show fundamental issues. Firing simple events via spread within a 3kHz real-time thread worked like a charm.

Going faster resulted in loads of spread errors (*Reason: unknown spread receive error*), so will check it with non-spread transports next to see if spread is the issue at that speed.

History

#1 - 05/21/2013 02:38 PM - J. Moringen

Maybe this should be explored in the dedicated rsb-realtime-cpp project?

I am leaning towards closing this and opening specific issues for that project. What do you think?

#2 - 05/21/2013 04:38 PM - Anonymous

Agreed.

#3 - 05/21/2013 04:39 PM - J. Moringen

- Status changed from *In Progress* to *Closed*

@Sebastian: please reopen, if you disagree.