

Robotics Service Bus - Bug #761

RSB is built with profiling instrumentation

12/13/2011 06:38 PM - J. Moringen

Status:	Resolved	Start date:	12/13/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	Packaging	Estimated time:	0.00 hour
Target version:			
Description			
<pre>\$ rsb_informer Elapsed time for 1200 messages sent: 0.07 s profiling:/home/jenkins:Cannot create directory profiling:/home/jenkins/workspace/rsb-cpp-trunk/label/ubuntu_lucid_32bit/rsb/build/src/CMakeFiles/rsbcore.dir/rsb/CommException.cpp.gccda:Skip profiling:/home/jenkins:Cannot create directory profiling:/home/jenkins/workspace/rsb-cpp-trunk/label/ubuntu_lucid_32bit/rsb/build/src/CMakeFiles/rsbcore.dir/rsb/Event.cpp.gccda:Skip profiling:/home/jenkins:Cannot create directory [...]</pre>			
We will probably have to create a separate job that builds RSB in release mode and creates the package.			

History

#1 - 12/13/2011 06:42 PM - J. Wienke

I vote for RelWithDebInfo to have meaningful backtraces.

#2 - 12/13/2011 06:46 PM - J. Moringen

(Should have been filed in support.cor-lab.org, sorry)

#3 - 12/29/2011 01:40 PM - J. Moringen

- Status changed from New to In Progress

- % Done changed from 0 to 60

There now is [a separate build job for packaging](#) which builds everything with RelWithDebInfo configuration and creates packages.

#4 - 12/29/2011 10:30 PM - J. Wienke

I think this is also required for project:rsb, to get completely rid of this.

#5 - 12/30/2011 11:29 PM - J. Moringen

See [# 335 in support.cor-lab.org](#).

#6 - 09/03/2013 10:01 AM - J. Wienke

- *Category changed from C++ to Packaging*
- *Status changed from In Progress to Resolved*
- *% Done changed from 60 to 100*

I think this is solved now. We haven't seen this since a long time and no specific job is stated here as being affected. We can reopen this with specific jobs in case this still appears.