

## Robotics Service Bus - Tasks #805

### Unify Name of Executables and Command Line Options for RSB Tools

01/16/2012 04:26 PM - S. Wrede

<b>Status:</b>	Resolved	<b>Start date:</b>	01/16/2012
<b>Priority:</b>	Low	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	0%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			

#### Description

If we have mutiple implementations of semantically similar tools such as the logger, we should use the same prefix for the executable.

The same is true for command line options (whenever possible). For instance, the loggers in C++/CL use the keywords format and style to denote the semantically same thing. That is unnecessary complexity.

#### Associated revisions

##### Revision cff632cb - 01/17/2012 01:39 AM - J. Moringen

Renamed commandline option in logger/main.cpp

refs #805

- logger/main.cpp (header): updated copyright  
(handleCommandline): changed commandline option format -> style

##### Revision ce86cacb - 01/17/2012 04:10 PM - J. Moringen

Added option description in manual/common.rst

refs #802, #805

- manual/common.rst: new file; contains description of common  
commandline options
- manual/tools.rst: include manual/common.rst

#### History

##### #1 - 01/17/2012 01:50 AM - J. Moringen

- *Description updated*
- *Status changed from New to In Progress*

##### #2 - 10/18/2015 08:44 PM - J. Moringen

- *Status changed from In Progress to Resolved*
- *Assignee set to J. Moringen*

Has been resolved for a long time.