Robotics Systems Types - Tasks #843
Initial Release

02/02/2012 03:17 PM - S. Wrede

Status:	Resolved		**Start date:**	02/02/2012
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:	1.0			

Description

Subtasks:

Tasks # 844: Create Version Identifier for Configuration of Dependant Packages	**Resolved**
Tasks # 845: Mark deprecated types as discouraged and move from stable to sandbox	**Resolved**
Tasks # 856: Document units and coordinate systems where necessary	**Resolved**
Tasks # 858: Move IDLs sandbox -> stable	**Resolved**

Related issues:

Blocked by Robotics Systems Types - Tasks # 863: Document IDLs in stable/rst/...	**Resolved**	**02/07/2012**
Blocked by Robotics Systems Types - Tasks # 862: Document InterauralTimeDiffe...	**Resolved**	**02/07/2012**

Associated revisions

Revision 9c111e6c - 02/09/2012 06:18 PM - J. Moringen

Bumped version in CMakeLists.txt

fixes #843

- CMakeLists.txt: version bump 1.0 -> 2.0

Revision 82d19acf - 02/09/2012 07:49 PM - J. Moringen

Version bump in manual/conf.py.in

refs #843

- manual/conf.py.in: bumped version 0.1 -> 2.0

History

#1 - 02/07/2012 04:37 PM - J. Moringen

- Target version set to 1.0

#2 - 02/07/2012 05:35 PM - J. Moringen

- Subject changed from Next RST Release to Initial Release

#3 - 02/09/2012 05:48 PM - J. Moringen

- Status changed from New to In Progress

- Assignee set to J. Moringen

#4 - 02/09/2012 06:19 PM - J. Moringen

- Status changed from In Progress to Resolved

Applied in changeset r227.