

## Robotics Systems Types - Tasks #845

Tasks # 843 (Resolved): Initial Release

### Mark deprecated types as discouraged and move from stable to sandbox

02/02/2012 03:23 PM - S. Wrede

<b>Status:</b>	Resolved	<b>Start date:</b>	02/02/2012
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	100%
<b>Category:</b>	protocol	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
Current candidates:			
<ul style="list-style-type: none"><li>- JointState</li><li>- ProprioceptionState</li></ul>			
Process:			
<ul style="list-style-type: none"><li>- Move proto file to sandbox</li><li>- Mark deprecation by adding a machine-readable comment to the proto-file itself</li></ul>			

#### Associated revisions

##### Revision e77418c6 - 02/07/2012 05:32 PM - J. Moringen

Marked JointState, ProprioceptionState as deprecated

fixes #845

- proto/sandbox/rst/kinematics/JointState.proto: moved  
proto/stable/rst/kinematics/JointState.proto ->  
proto/sandbox/rst/kinematics/JointState.proto; marked as deprecated  
via doxygen-like comment
- proto/sandbox/rst/kinematics/ProprioceptionState.proto: similar

#### History

##### #1 - 02/07/2012 04:08 PM - J. Moringen

- Subject changed from *Mark Deprecated Types as Discouraged and from Stable to Sandbox* to *Mark deprecated types as discouraged and move from stable to sandbox*
- Description updated

##### #2 - 02/07/2012 05:33 PM - J. Moringen

- Status changed from *New* to *Resolved*
- % Done changed from 0 to 100

Applied in changeset r204.