

Robotics Systems Types - Tasks #845

Tasks # 843 (Resolved): Initial Release

Mark deprecated types as discouraged and move from stable to sandbox

02/02/2012 03:23 PM - S. Wrede

Status:	Resolved	Start date:	02/02/2012
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	protocol	Estimated time:	0.00 hour
Target version:			
Description			
Current candidates:			
<ul style="list-style-type: none">- JointState- ProprioceptionState			
Process:			
<ul style="list-style-type: none">- Move proto file to sandbox- Mark deprecation by adding a machine-readable comment to the proto-file itself			

Associated revisions

Revision e77418c6 - 02/07/2012 05:32 PM - J. Moringen

Marked JointState, ProprioceptionState as deprecated

fixes #845

- proto/sandbox/rst/kinematics/JointState.proto: moved
proto/stable/rst/kinematics/JointState.proto ->
proto/sandbox/rst/kinematics/JointState.proto; marked as deprecated
via doxygen-like comment
- proto/sandbox/rst/kinematics/ProprioceptionState.proto: similar

History

#1 - 02/07/2012 04:08 PM - J. Moringen

- Subject changed from Mark Deprecated Types as Discouraged and from Stable to Sandbox to Mark deprecated types as discouraged and move from stable to sandbox
- Description updated

#2 - 02/07/2012 05:33 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r204.