

## Robotics Systems Types - Tasks #856

Tasks # 843 (Resolved): Initial Release

### Document units and coordinate systems where necessary

02/07/2012 04:40 PM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	02/07/2012
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	100%
<b>Category:</b>	documentation	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	1.0		
<b>Description</b>			

#### Associated revisions

##### Revision a4095165 - 02/07/2012 05:16 PM - J. Moringen

Documented units in some \*.proto files

fixes #856

- proto/sandbox/rst/InstantaneousPhase.proto: document units of fields that implicitly have an associated unit
- proto/sandbox/rst/geometry/Translation.proto: likewise
- proto/stable/rst/geometry/BoundingBox.proto: likewise
- proto/stable/rst/vision/Faces.proto: likewise
- proto/stable/rst/vision/Image.proto: likewise

#### History

##### #1 - 02/07/2012 04:40 PM - J. Moringen

- *Category set to documentation*
- *Target version set to 1.0*

##### #2 - 02/07/2012 05:16 PM - J. Moringen

- *Status changed from In Progress to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset r202.