Robotics Service Bus - Tasks #914 Configure logging using rsb config

03/02/2012 02:42 PM - J. Wienke

Status:	Resolved	Start date:	03/02/2012	
Priority:	Normal	Due date:		
Assignee:	J. Wienke	% Done:	100%	
Category:	C++	Estimated time:	0.00 hour	
Target version:	0.6			
Description				
Since it is now possi	ble to configure the rsc logging s	ystem using a file, enable this in RS	B.	
	ble to configure the rsc logging s	ystem using a file, enable this in RS	SB.	
Related issues:	ble to configure the rsc logging s		B. Resolved	03/02/2012
Related issues: Related to Robotics Se		tor out configuration		03/02/2012 03/02/2012

Associated revisions

Revision 0f736bdd - 03/02/2012 03:48 PM - J. Wienke

Configure logging using the usual configuration file cascade.

The implementation basically duplicates the cascade as it is not very well factored right now. This needs refactoring.

refs #914

Revision f9d32799 - 03/02/2012 08:27 PM - J. Moringen

Don't fail on missing rsb.conf in src/rsb/Factory.cpp

refs #914, should fix the windows build

 src/rsb/Factory.cpp: catch exceptions thrown during attempts to read system-wide and user-specific rsb.conf configuration files

History

#1 - 03/02/2012 03:59 PM - J. Wienke

- % Done changed from 0 to 60

Basicaly integrated now in a not so nice fashion (#916). However, environment parsing is broken right now because the parser makes everything lower-case.

#2 - 03/02/2012 04:44 PM - J. Wienke

- Status changed from In Progress to Resolved

This is a deeper specification problem of RSC (see #918). Postponed until that issue is fixed.

#3 - 03/02/2012 08:28 PM - J. Moringen

- % Done changed from 60 to 100