Robotics Service Bus - Tasks #914
Configure logging using rsb config

03/02/2012 02:42 PM - J. Wienke

Status:	Resolved	**Start date:**	03/02/2012
Priority:	Normal	**Due date:**	
Assignee:	J. Wienke	**% Done:**	100%
Category:	C++	**Estimated time:**	0.00 hour
Target version:	0.6		

Description

Since it is now possible to configure the rsc logging system using a file, enable this in RSB.

Related issues:

Related to Robotics Service Bus - Enhancement # 916: Factor out configuration...	**Resolved**	**03/02/2012**
Related to Robotics Systems Commons - Enhancement # 918: Specify key handling...	**Resolved**	**03/02/2012**
Blocked by Robotics Systems Commons - Bug # 915: Configuration provider objec...	**Resolved**	**03/02/2012**

Associated revisions

Revision 0f736bdd - 03/02/2012 03:48 PM - J. Wienke

Configure logging using the usual configuration file cascade.

The implementation basically duplicates the cascade as it is not very well factored right now. This needs refactoring.

refs #914

Revision f9d32799 - 03/02/2012 08:27 PM - J. Moringen

Don't fail on missing rsb.conf in src/rsb/Factory.cpp

refs #914, should fix the windows build

- src/rsb/Factory.cpp: catch exceptions thrown during attempts to read
  system-wide and user-specific rsb.conf configuration files

History

#1 - 03/02/2012 03:59 PM - J. Wienke

- % Done changed from 0 to 60

Basicaly integrated now in a not so nice fashion (#916). However, environment parsing is broken right now because the parser makes everything lower-case.

#2 - 03/02/2012 04:44 PM - J. Wienke

- Status changed from In Progress to Resolved

This is a deeper specification problem of RSC (see #918). Postponed until that issue is fixed.

#3 - 03/02/2012 08:28 PM - J. Moringen

- % Done changed from 60 to 100