Robotics Service Bus - Enhancement #916
Factor out configuration cascade to RSC

03/02/2012 03:49 PM - J. Wienke

Status:	Resolved		**Start date:**	03/02/2012
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:	C++		**Estimated time:**	0.00 hour
Target version:	rsb-0.9			

Description

ParticipantConfig and logging configuration need the same cascade of files to read from. However, this is currently tightly integrate in ParticipantConfig.

Extract the common cascade we use (to RSC) and let a method provide a list of ConfigFileSources. PArticipantConfig and logging configuration just iterate over this list.

Related issues:

Related to Robotics Service Bus - Tasks # 914: Configure logging using rsb co...	**Resolved**	**03/02/2012**

Associated revisions

Revision c3c4f0c6 - 10/02/2012 11:37 AM - J. Moringen

Use rsc::config::configure for logging, participant configs

fixes #916

- src/rsb/Factory.cpp: in Factory constructor, use
  rsc::config::configure instead of configureSubsystem; removed
  configureSubsystem
- src/rsb/ParticipantConfig.{h,cpp}: removed fromFile,
  fromEnvironment, fromConfiguration
- test/rsb/ParticipantConfigTest.cpp: construct ConfigFileSource
  objects manually instead of using fromFile
- test/rsb/FactoryTest.cpp: do not test any assumptions regarding the
  default configuration

Revision 70538bb6 - 10/02/2012 07:28 PM - J. Moringen

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  rsc::config::configure instead of configureSubsystem; removed
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- test/rsb/FactoryTest.cpp: do not test any assumptions regarding the
  default configuration

History

#1 - 06/18/2012 01:53 PM - J. Moringen

- Target version changed from rsb-0.7 to rsb-0.9

#2 - 10/02/2012 10:43 AM - J. Moringen

- Status changed from New to In Progress

- Assignee set to J. Moringen

#3 - 10/02/2012 12:05 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:c3c4f0c666487d285f1135545edc150fee5e5906.