Robotics Service Bus - Tasks #942
Create generic send tool

03/13/2012 01:14 AM - J. Moringen

Status:	Resolved		**Start date:**	03/13/2012
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:	Common Lisp Tools		**Estimated time:**	0.00 hour
Target version:	rsb-0.7			

Description

It would be useful to have a tool, maybe called send, to create and send simple RSB events.

- The tool should support simple payloads (like the call tool already does)
- The tool should support XML payloads (later, see #1002)
- The tool should support protocol buffer payloads (later)
    Maybe via JSON input syntax?

Other stuff

- Test (later)

Associated revisions

Revision 1ee6eed5 - 03/13/2012 04:37 AM - J. Moringen

Added send tool in send/{package, main}*.lisp

refs #942

- send/main.lisp: new file; contains main function of the send
    utility
- send/package.lisp: new file; contains package definition for the
    send utility
- cl-rsb-tools-send.asd: new file; system definition for send
    utility
- main/main.lisp (**filename->entry-point**): added entry for send
    program
- cl-rsb-tools-main.asd (system cl-rsb-tools-main): added system
    dependency on cl-rsb-tools-send
- CMakeLists.txt: added send program to TOOLS

Revision e4f7df2c - 03/13/2012 01:44 PM - J. Moringen

Added man-page for send tool in manual/send.rst

refs #942

- manual/conf.py.in: added man-page for send program
- manual/send.rst: new file; man-page for send program
- manual/tools.rst: include manual/send.rst

History

#1 - 03/13/2012 04:38 AM - J. Moringen

- Description updated

- Status changed from New to In Progress

- % Done changed from 0 to 40

#2 - 06/18/2012 01:46 PM - J. Moringen

- Description updated

- Status changed from In Progress to Resolved

- % Done changed from 40 to 100