Robot Control Interface - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
2321	Tasks	New	Low	Implement Weights type		06/12/2015 03:12 PM		0
2056	Feature	New	Low	Calculate scalar angle between orientations		10/10/2014 03:23 PM	Software	0
1789	Tasks	New	Normal	RCI::Orientation should be represented as unit quaternions		03/06/2014 04:06 PM		0
1713	Bug	Feedback	Normal	RCI is getting messed up with Torques, JointTorques and TorqueSensing		01/06/2014 08:33 PM	Modeling	0
1656	Bug	New	Normal	rci::Orientation->asRotationMatrix() crashes when build against /vol/amarsi/x86-64-precise/trunk		11/11/2013 10:56 AM		0
1598	Tasks	Feedback	Normal	Release rci 0.4		08/21/2013 01:12 PM		0
1506	Bug	New	Normal	call to implicitly-deleted copy constructor of 'ControlAspectPtr'		08/12/2013 01:47 PM		0
1431	Enhancement	New	Normal	debian package should confirm more strongly to the debian policy		09/12/2013 04:25 PM		0
1255	Enhancement	New	Normal	rci::Orientation: Check given matrix for being a rotation matrix		08/12/2013 02:05 PM		0
1043	Bug	Feedback	High	Modelisation of Wrench seems wrong	A. Tuleu	01/20/2014 08:59 AM	Modeling	80
1021	Enhancement	New	Low	Use sphinx' citation feature in manual		09/12/2013 04:25 PM		0
978	Tasks	New	Urgent	NaN when converting in singularities		09/12/2013 04:25 PM		20
944	Feature	Feedback	Normal	Provide pose interpolation		09/12/2013 04:25 PM		0
904	Feature	New	Normal	Orientation interface methods for euler angles zyx		03/07/2012 12:15 PM		0
883	Tasks	New	Normal	Rethink shared pointers		08/12/2013 02:09 PM		0
278	Feature	New	Normal	Check on making constructors protected/private to just use boost pointers		08/12/2013 02:16 PM		0