

Robot Control Interface - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
874	Feature	Resolved	Immediate	CartesianPose: implement from/to methods for homogeneous transformation matrix		02/14/2012 03:19 PM		100
2379	Bug	Resolved	Urgent	Wrong URL in project description site	S. Wrede	12/14/2015 05:22 PM		100
1254	Bug	Closed	Urgent	LWRRaveEnvironment example is not running	D. Seidel	01/16/2014 11:19 AM		100
1715	Feature	Resolved	High	Provide better interface for creation of wrench		01/20/2014 09:03 AM	Software	100
1714	Feature	Resolved	High	Provide rci::wrench converter in rst-converters		01/20/2014 09:09 AM	Software	100
893	Bug	Resolved	High	Copy constructor of Pose is not working		02/24/2012 06:10 PM		100
1789	Tasks	New	Normal	RCI::Orientation should be represented as unit quaternions		03/06/2014 04:06 PM		0
1713	Bug	Feedback	Normal	RCI is getting messed up with Torques, JointTorques and TorqueSensing		01/06/2014 08:33 PM	Modeling	0
1712	Bug	Resolved	Normal	RCI requires at least NemoMath0.4 but cmake does not declare so		01/05/2014 06:36 PM		100
1435	Bug	Resolved	Normal	Wrong spelling of CartesianValues::asRotationMatrix		08/12/2013 02:01 PM		100
1434	Bug	Resolved	Normal	Orientation::rotateby method is wrong		02/21/2013 01:51 PM		100
1255	Enhancement	New	Normal	rci::Orientation: Check given matrix for being a rotation matrix		08/12/2013 02:05 PM		0
995	Support	Rejected	Normal	CartesianForces is only 3-dimensional		06/06/2012 11:07 AM		0
944	Feature	Feedback	Normal	Provide pose interpolation		09/12/2013 04:25 PM		0
934	Bug	Resolved	Normal	asCompactAxisAngles() results in 'NaN' ...		03/08/2012 08:00 PM		100