

Robot Control Interface - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|------|-------------|----------|----------|---|----------|---------------------|----------|--------|
| 2056 | Feature | New | Low | Calculate scalar angle between orientations | | 10/10/2014 03:23 PM | Software | 0 |
| 1021 | Enhancement | New | Low | Use sphinx' citation feature in manual | | 09/12/2013 04:25 PM | | 0 |
| 1713 | Bug | Feedback | Normal | RCI is getting messed up with Torques, JointTorques and TorqueSensing | | 01/06/2014 08:33 PM | Modeling | 0 |
| 1431 | Enhancement | New | Normal | debian package should confirm more strongly to the debian policy | | 09/12/2013 04:25 PM | | 0 |
| 1255 | Enhancement | New | Normal | rci::Orientation: Check given matrix for being a rotation matrix | | 08/12/2013 02:05 PM | | 0 |
| 944 | Feature | Feedback | Normal | Provide pose interpolation | | 09/12/2013 04:25 PM | | 0 |
| 883 | Tasks | New | Normal | Rethink shared pointers | | 08/12/2013 02:09 PM | | 0 |
| 278 | Feature | New | Normal | Check on making constructors protected/private to just use boost pointers | | 08/12/2013 02:16 PM | | 0 |
| 978 | Tasks | New | Urgent | NaN when converting in singularities | | 09/12/2013 04:25 PM | | 20 |