

Robot Control Interface - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|------|-------------|----------|----------|---------------------------------------------------------------------------|----------|---------------------|---------------|--------|
| 1692 | Bug | Resolved | Urgent | rci doesn't build with rsc>=0.10 | | 12/19/2013 10:21 AM | Configuration | 100 |
| 978 | Tasks | New | Urgent | NaN when converting in singularities | | 09/12/2013 04:25 PM | | 20 |
| 1715 | Feature | Resolved | High | Provide better interface for creation of wrench | | 01/20/2014 09:03 AM | Software | 100 |
| 2123 | Tasks | Resolved | Normal | Use Eigen3 by default, not Eigen2 | | 12/05/2014 04:08 PM | Software | 80 |
| 1895 | Bug | Resolved | Normal | Tests failing on ubuntu trusty 32 bit | | 07/14/2015 02:39 PM | Software | 0 |
| 1865 | Bug | Resolved | Normal | RCI tests don't build on Ubuntu trusty | | 04/29/2014 04:40 PM | Software | 100 |
| 1713 | Bug | Feedback | Normal | RCI is getting messed up with Torques, JointTorques and TorqueSensing | | 01/06/2014 08:33 PM | Modeling | 0 |
| 1431 | Enhancement | New | Normal | debian package should confirm more strongly to the debian policy | | 09/12/2013 04:25 PM | | 0 |
| 1255 | Enhancement | New | Normal | rci::Orientation: Check given matrix for being a rotation matrix | | 08/12/2013 02:05 PM | | 0 |
| 944 | Feature | Feedback | Normal | Provide pose interpolation | | 09/12/2013 04:25 PM | | 0 |
| 883 | Tasks | New | Normal | Rethink shared pointers | | 08/12/2013 02:09 PM | | 0 |
| 278 | Feature | New | Normal | Check on making constructors protected/private to just use boost pointers | | 08/12/2013 02:16 PM | | 0 |
| 2056 | Feature | New | Low | Calculate scalar angle between orientations | | 10/10/2014 03:23 PM | Software | 0 |
| 1021 | Enhancement | New | Low | Use sphinx' citation feature in manual | | 09/12/2013 04:25 PM | | 0 |