

## Robot Control Interface - Issues

| #    | Tracker | Status   | Priority | Subject                              | Assignee | Updated             | Category | % Done |
|------|---------|----------|----------|--------------------------------------|----------|---------------------|----------|--------|
| 2123 | Tasks   | Resolved | Normal   | Use Eigen3 by default, not Eigen2    |          | 12/05/2014 04:08 PM | Software | 80     |
| 978  | Tasks   | New      | Urgent   | NaN when converting in singularities |          | 09/12/2013 04:25 PM |          | 20     |
| 883  | Tasks   | New      | Normal   | Rethink shared pointers              |          | 08/12/2013 02:09 PM |          | 0      |