

Robot Control Interface - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
874	Feature	Resolved	Immediate	CartesianPose: implement from/to methods for homogeneous transformation matrix		02/14/2012 03:19 PM		100
1344	Bug	Resolved	Immediate	Debian packaging mark dependency on librs0.8 but actual binary depends on librs0.9 !!!		01/21/2013 08:16 PM		100