

Robot Control Interface - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|------|---------|----------|-----------|--|----------|---------------------|----------|--------|
| 874 | Feature | Resolved | Immediate | CartesianPose: implement from/to methods for homogeneous transformation matrix | | 02/14/2012 03:19 PM | | 100 |
| 1344 | Bug | Resolved | Immediate | Debian packaging mark dependency on librsc0.8 but actual binary depends on librsc0.9 !!! | | 01/21/2013 08:16 PM | | 100 |