

Robot Control Interface - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
944	Feature	Feedback	Normal	Provide pose interpolation		09/12/2013 04:25 PM		0
904	Feature	New	Normal	Orientation interface methods for euler angles zyx		03/07/2012 12:15 PM		0
278	Feature	New	Normal	Check on making constructors protected/private to just use boost pointers		08/12/2013 02:16 PM		0
2056	Feature	New	Low	Calculate scalar angle between orientations		10/10/2014 03:23 PM	Software	0