

Robot Control Interface - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
2444	Feature	Resolved	High	Update for RCI types JointVelocities and JointAccelerations	D. Wigand	12/11/2015 11:50 AM	Software	100
2380	Feature	Resolved	High	new RCI JointAccelerations		09/22/2015 04:10 PM		100
2056	Feature	New	Low	Calculate scalar angle between orientations		10/10/2014 03:23 PM	Software	0
1715	Feature	Resolved	High	Provide better interface for creation of wrench		01/20/2014 09:03 AM	Software	100
1714	Feature	Resolved	High	Provide rci::wrench converter in rst-converter		01/20/2014 09:09 AM	Software	100
1360	Feature	Resolved	Normal	Provide RawData DTO		01/28/2013 11:58 AM		100
1359	Feature	Resolved	Normal	Provide generic "raw data" dto		08/12/2013 02:05 PM		100
944	Feature	Feedback	Normal	Provide pose interpolation		09/12/2013 04:25 PM		0
904	Feature	New	Normal	Orientation interface methods for euler angles zyx		03/07/2012 12:15 PM		0
874	Feature	Resolved	Immediate	CartesianPose: implement from/to methods for homogeneous transformation matrix		02/14/2012 03:19 PM		100
851	Feature	Resolved	High	AxisAngle / CompactAxisAngle conversions for Rotation		02/04/2012 04:48 PM		100
279	Feature	Resolved	Normal	Handle setting of lastcommand/lastcommanded		08/12/2013 02:15 PM		0
278	Feature	New	Normal	Check on making constructors protected/private to just use boost pointers		08/12/2013 02:16 PM		0
275	Feature	Resolved	Normal	Factories for DTOs		08/12/2013 02:13 PM		0