

## Robotics Service Bus - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
1613	Bug	Rejected	Normal	rsb-loggercpp0.10 (installed in toolkit-nightly) crashes on start	J. Wienke	09/05/2013 02:28 PM	C++	0
495	Bug	Rejected	Normal	Check if Event is Send to Sub-Scopes of Informer Scope	S. Wrede	08/10/2011 05:54 PM	Java	0
1421	Bug	Closed	Normal	Verify that string encoding change complies to TIDELog specification		10/11/2013 06:27 PM	Documentation	80
486	Bug	Resolved	Normal	Converters for Fundamental Types are not Implemented [Common Lisp]	J. Moringen	06/16/2016 06:46 PM	Common Lisp	100
1816	Bug	Resolved	High	rsb-python 0.10 not deployed to pypi	J. Wienke	03/19/2014 03:01 PM	Python	100
1728	Bug	Resolved	High	Error in rsb.pc		01/27/2014 04:44 PM	Configuration	100
1695	Bug	Resolved	Normal	Fix failing tests of tools	J. Moringen	01/14/2014 06:22 PM	Commandline Tools	100
1662	Bug	Resolved	High	6c1e55c6 broke converter selection - and unit tests did not catch it	J. Moringen	11/22/2013 03:38 PM	C++	100
1588	Bug	Resolved	Normal	Failing test in timesync sub-project	J. Wienke	09/05/2013 05:32 PM	Timesync	100
1081	Bug	Resolved	Normal	Precise GUI package manager automatically proposes a source DEB source, manual should inform about deactivating it again.	J. Wienke	09/03/2013 03:54 PM	Installation	100
1602	Bug	Resolved	Normal	NullPointerException during Bus deactivation	J. Wienke	09/02/2013 04:03 PM	Java	100
1304	Bug	Resolved	Normal	Check if Java Implementation Throws Expected Exceptions if Spread is not Available	S. Wrede	08/27/2013 10:23 AM	Java	100
1488	Bug	Resolved	Normal	Socket transport between cpp and cl mostly fails on mac	J. Moringen	08/23/2013 08:10 PM	Socket Transport	100
1158	Bug	Resolved	High	Sequence number increment is not atomic	J. Wienke	08/19/2013 08:29 AM	C++	100
559	Bug	Resolved	Normal	Use dynamic spread library by default	J. Wienke	09/08/2011 04:16 PM	C++	100