

Robotics Service Bus - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
471	Feature	New	Normal	Support for RPC clients which do not require a running server part		07/07/2016 10:10 AM		0
1745	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	C++	0
1746	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	Java	0
1747	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	Python	0
2185	Feature	New	Normal	Provide Contrib Library or Folder for Community Additions		06/14/2016 09:53 AM	Packaging	0
1707	Feature	New	Low	Support Java as a client language		04/17/2015 03:05 AM	Java Client API	0
1922	Feature	New	Low	Include environment variables in introspection messages describing processes		04/24/2015 05:38 PM	Introspection	0
1102	Feature	In Progress	High	Use data type definitions stored in log files	J. Moringen	04/03/2017 06:42 PM	Backend	30
382	Feature	In Progress	Normal	Interaction with Foreign Nameservice	J. Moringen	06/08/2016 02:21 PM	ROS Connector	50
1706	Feature	In Progress	Normal	Support C++ as a client language	J. Moringen	11/10/2015 11:50 AM	C++ Client API	50
1770	Feature	In Progress	Normal	Add TYPE block to TIDELog backend	J. Moringen	04/02/2017 10:52 AM	TIDELog Backend	20
1771	Feature	In Progress	Normal	Add META block to TIDELog backend	J. Moringen	04/02/2017 10:52 AM	TIDELog Backend	20
2051	Feature	In Progress	Normal	Qt-based graphical event logger	R. Haschke	04/24/2015 05:38 PM	C++ Tools	80
710	Feature	Resolved	Normal	Implement socket-based transport	J. Moringen	11/16/2011 02:53 AM	C++	100
340	Feature	Feedback	Normal	Implement Distributed Namensservice		12/22/2015 11:19 AM	Introspection	0
2227	Feature	Feedback	Normal	Symlinks/Aliases for Scopes	C. Leichsenring	06/09/2016 01:46 PM	Protocol	0