

Robotics Service Bus - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
1257	Tasks	Resolved	Normal	Add ordering constraint for converter registration to troubleshooting section		12/20/2012 05:23 PM	Documentation	100
1202	Tasks	Resolved	Normal	Apply Workaround for Concept Documentation	S. Wrede	10/15/2012 01:09 PM	Documentation	100
1187	Tasks	Resolved	High	Fix so_version of 0.7		10/04/2012 04:12 PM	Configuration	100
926	Tasks	Resolved	Normal	Release version 0.7	J. Moringen	08/11/2012 05:35 AM	Release Management	100
1037	Tasks	Resolved	Normal	Implement error handling subsystem	J. Moringen	08/10/2012 09:12 PM	Common Lisp	100
900	Tasks	Resolved	Normal	Finalize initial version of RSB manual	J. Moringen	08/04/2012 07:06 PM	Documentation	100
1044	Tasks	Resolved	Normal	Change of log level for socket disconnection message	J. Wienke	07/22/2012 04:12 PM	C++	100
1060	Tasks	Resolved	Normal	Cross-reference individual manuals		07/20/2012 12:45 AM	Documentation	100
1006	Tasks	Resolved	High	Create fancy title page for RSB manual		07/18/2012 11:25 PM	Documentation	100
1050	Tasks	Resolved	Normal	Allow building Debian package with and without Spread support	J. Moringen	06/29/2012 08:34 PM	Packaging	100
715	Tasks	Resolved	Normal	Integrate socket-based transport into integration test	J. Moringen	06/27/2012 03:10 AM	Language Integration	100
1020	Tasks	Resolved	Low	Document protocol used by socket transport	J. Moringen	06/25/2012 01:30 PM	Documentation	100
1014	Tasks	Resolved	Normal	Make Spread conditionally dependant in Python RSB implementation	J. Wienke	06/22/2012 03:20 PM	Python	100
847	Tasks	Resolved	Normal	Make buffer write back configurable	J. Moringen	06/21/2012 03:41 AM		100
942	Tasks	Resolved	Normal	Create generic send tool	J. Moringen	06/18/2012 01:46 PM	Common Lisp Tools	100
353	Tasks	Resolved	Normal	Document Installation using Binary Packages		04/19/2012 05:05 PM	Documentation	100
880	Tasks	Resolved	Normal	Implement timeline-ish formatting style	J. Moringen	04/10/2012 08:58 PM	Common Lisp Tools	100
716	Tasks	Resolved	Normal	Document cause vectors in [[Events]]	J. Wienke	04/02/2012 01:05 PM	Documentation	60
932	Tasks	Resolved	Normal	Implement --start-time and --end-time for bag-{cat,play}	J. Moringen	03/12/2012 04:41 PM		100