

Robotics Service Bus - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|---------|----------|----------|--|-------------|---------------------|-------------------|--------|
| 727 | Feature | Resolved | Normal | Implement Connector Subsystem | J. Moringen | 03/02/2012 08:45 PM | Python | 100 |
| 733 | Feature | Resolved | High | Configurable output for bag-cat | J. Moringen | 12/12/2011 10:56 PM | | 100 |
| 734 | Feature | Resolved | Normal | Make Spread Transport Compilation Optional | J. Wienke | 01/07/2012 10:21 AM | Spread Connector | 100 |
| 735 | Feature | Resolved | Normal | Newer tool versions should be able to read files written by older versions | J. Moringen | 03/06/2012 08:09 PM | | 100 |
| 736 | Feature | Resolved | Normal | Logger should support printing of event collections | J. Wienke | 01/18/2012 09:05 AM | C++ Tools | 100 |
| 737 | Feature | Resolved | Normal | Logger should support printing of event collections | J. Moringen | 03/06/2012 08:08 PM | Common Lisp Tools | 100 |
| 850 | Feature | Resolved | Normal | Global rsb.conf file | J. Moringen | 03/01/2012 08:23 PM | Configuration | 100 |