

## Robotics Service Bus - Issues

| #    | Tracker | Status   | Priority | Subject  | Assignee    | Updated             | Category           | % Done |
|------|---------|----------|----------|--|-------------|---------------------|--------------------|--------|
| 2386 | Bug     | Resolved | Normal   | C++ spread plugin crashes when using multiple threads + informers on Windows | J. Moringen | 05/19/2017 01:30 PM | Spread Connector   | 100    |
| 2710 | Feature | Resolved | Normal   | Allow synchronous RPC-calls to timeout                                       | J. Moringen | 09/18/2017 03:00 PM | Python             | 100    |
| 2537 | Feature | Resolved | Low      | try-with-resources   | J. Moringen | 10/10/2017 06:10 PM | Java               | 100    |
| 2719 | Tasks   | Resolved | Normal   | Release version 0.17   | J. Moringen | 10/18/2017 01:21 PM | Release Management | 100    |
| 1028 | Tasks   | Resolved | Normal   | Expose connector "remoteness" in transport package [Java]                    | J. Moringen | 09/18/2017 07:37 PM | Java               | 100    |