

Robotics Service Bus - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|------|---------|----------|----------|--|-------------|---------------------|--------------------|--------|
| 2386 | Bug | Resolved | Normal | C++ spread plugin crashes when using multiple threads + informers on Windows | J. Moringen | 05/19/2017 01:30 PM | Spread Connector | 100 |
| 2710 | Feature | Resolved | Normal | Allow synchronous RPC-calls to timeout | J. Moringen | 09/18/2017 03:00 PM | Python | 100 |
| 2537 | Feature | Resolved | Low | try-with-resources | J. Moringen | 10/10/2017 06:10 PM | Java | 100 |
| 2719 | Tasks | Resolved | Normal | Release version 0.17 | J. Moringen | 10/18/2017 01:21 PM | Release Management | 100 |
| 1028 | Tasks | Resolved | Normal | Expose connector "remoteness" in transport package [Java] | J. Moringen | 09/18/2017 07:37 PM | Java | 100 |