

Robotics Service Bus - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|---------|----------|----------|-------------------------------------------------------|-------------|---------------------|----------|--------|
| 311 | Bug | Resolved | Normal | Remove any Output that bypasses the Logging Machinery | J. Moringen | 05/24/2011 05:20 PM | C++ | 100 |
| 306 | Bug | Resolved | Normal | Apply QoS from config to ports | S. Wrede | 05/25/2011 01:16 PM | Java | 100 |
| 307 | Bug | Resolved | Normal | QoS options are not respected by connectors | J. Moringen | 05/23/2011 05:34 PM | Python | 100 |