

Robotics Service Bus - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
2673	Feature	In Progress	Normal	In addition to DISPLAY_NAME, the introspection system should accept a DISPLAY_VERSION or similar	J. Moringen	10/16/2017 09:23 PM	Introspection	0
2648	Feature	New	Low	Setters for TimesyncStrategy options		12/12/2018 03:10 PM	Timesync	0
2555	Feature	In Progress	Normal	Allow easy debugging of RSB configuration	J. Moringen	10/16/2017 09:23 PM	Configuration	90
2227	Feature	Feedback	Normal	Symlinks/Aliases for Scopes	C. Leichsenring	06/09/2016 01:46 PM	Protocol	0
2185	Feature	New	Normal	Provide Contrib Library or Folder for Community Additions		06/14/2016 09:53 AM	Packaging	0
2170	Feature	New	Low	Visual indication when rsb-logger* (or any other rsb-tool) is ready	J. Moringen	10/16/2017 09:23 PM	Common Lisp Tools	0
2139	Feature	New	Normal	Finalize introspection implementation		10/16/2017 09:23 PM	Introspection	16
2138	Feature	New	Normal	Allow constructing scopes from a list of component strings (potentially single component)		10/16/2017 09:23 PM		0
2051	Feature	In Progress	Normal	Qt-based graphical event logger	R. Haschke	04/24/2015 05:38 PM	C++ Tools	80
1993	Feature	In Progress	Low	Rebuild introspection database when clock jumps	J. Moringen	10/16/2017 09:23 PM	Introspection	50
1982	Feature	In Progress	Normal	Enable introspection senders by default?	J. Moringen	10/16/2017 09:23 PM	Introspection	60
1922	Feature	New	Low	Include environment variables in introspection messages describing processes		04/24/2015 05:38 PM	Introspection	0
1870	Feature	New	Normal	Allow (optional) parallel method calls		06/30/2016 12:36 PM		0
1839	Feature	In Progress	Normal	Reference documentation in conditions	J. Moringen	10/16/2017 09:22 PM	Common Lisp	70
1776	Feature	In Progress	Normal	Highlight interesting things in logger/bag-cat output	J. Moringen	10/16/2017 09:23 PM	Common Lisp Tools	30
1767	Feature	Feedback	Low	Export default plugin folder		10/16/2017 09:23 PM	Configuration	50
1747	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	Python	0
1746	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	Java	0
1745	Feature	New	Normal	Implement introspection event receiver and client API		11/22/2016 08:22 PM	C++	0
1149	Feature	Feedback	Normal	Allow checking if handlers are registered in Listener		10/16/2017 09:22 PM	C++	0
1139	Feature	In Progress	Normal	Reference documentation in error reports		10/16/2017 09:22 PM	Documentation	70
729	Feature	New	Normal	Allow regex-based converter selection for deserializing		11/23/2011 01:26 PM	Java	0
674	Feature	New	Normal	Implement ErrorHandler subsystem in Java		10/16/2017 09:22 PM	Java	0
471	Feature	New	Normal	Support for RPC clients which do not require a running server part		07/07/2016 10:10 AM		0
382	Feature	In Progress	Normal	Interaction with Foreign Nameservice	J. Moringen	06/08/2016 02:21 PM	ROS Connector	50
381	Feature	New	Low	Timestamp compatilby to ROS and YARP		06/21/2011 07:43 PM	Specification	0
340	Feature	Feedback	Normal	Implement Distributed Namingservice		12/22/2015 11:19 AM	Introspection	0
318	Feature	New	Normal	Support QoS in Spread connector	J. Moringen	04/19/2012 05:27 PM	Common Lisp	0
45	Feature	New	Normal	Add Conditional Parsing for User Data in Receiver Process	S. Wrede	08/18/2010 09:00 PM	C++	0