RSBag

	2020-1			2020-2				2020-3				2020-4					2020-5				2020-6					
		2 3			5 6		7 8	9	1	0 11	1	12 13	3 1	4	15	16	17	18	19	20	21	22	23	24	25	26
Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Support linked media files () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined () show-progress online help doesn't () Allow to specify output stream () Robotics Service Bus - rsb-1.0 Verify Elan backend Use data type definitions stored () Rename bag-merge -> bag-transform Support C++ as a client language Support Java as a client language	R R R In In N In N In N N N N N N N R N In	oboti SBag oboti Prog Prog Prog Prog Prog Prog Prog Prog	ics Se gress gress gress gress gress gress % gress gress % gress gress gress gress gress gress gress gress gress	209 409 209 309 609	ce Bu	s -I	7 8	8 30%		0 11	11	12 1:	3 1	4	15	16	17	18	19	20	21	222	2 23	24	25	26

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add TTPE block to TibeLog backetid	In Progress 209/
Add META block to TIDELog backend	In Progress 20%

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