## RSBag

	2021-10		2021-11		2	021-12			202	22-1			20	)22-2			202	2-3	
	40 41 42 43		45 46	47 4	8 49	50 5	51 5	52 1	2	3	4	5	6	7	8	9	10 1	1 12	
Robotics Service Bus	Robotics Service	e Bus	•		•		•	•			-						-		
RSBag	RSBag			0.000/															
Robotics Service Bus - rsb-0.18	Robotics Service		-rsb-0.1	8 30%															
Which timestamps should be set ()	In Progress 30%																		
Newer tool versions should be able ()	In Progress 50%	•																	
Computation of channel format is ()	New 0%																		
Extend Elan backend	In Progress 20%	•																	
Support proper temporal intervals ()	New 0%																		
Support linked media files ()	In Progress 40%	•																	
Allow limiting recording time	New 0%																		
bag record: Make status output ()	In Progress 50%																		
Minimal support for ROSbag file ()	In Progress 60%	•																	
Support explicit backend selection	New 0%																		
Store start and end timestamp of ()	New 0%																		
bag record: Start timestamp for ()	New 0%																		
Allow to deduplicate participants ()	New 0%																		
Bag as bus server crashes in case ()	New 0%																		
Events with same timestamps are ()	In Progress 20%	•																	
Flush indices based on combined ()	New 0%																		
show-progress online help doesn't ()	New 0%																		
Allow to specify output stream ()	New 0%	_																	
Robotics Service Bus - rsb-1.0	Robotics Service	e Bus	-rsb-1.0	16%															
Verify Elan backend	New 0%																		
Use data type definitions stored ()	In Progress 30%																		
Rename bag-merge -> bag-transform	In Progress 60%																		
Support C++ as a client language	In Progress 50%	•																	
Support Java as a client language	New 0%																		
Document C++ client API	New 0%																		

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%

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