RSBag

	2020-12 2021-1		20	21-2		2021-3			2021-4			2021-5				
	50 51 52 5		2 3	4	56	78	B 9	10 11	12	13 14	4 15 1	ô 17	18	19	20	21
Robotics Service Bus RSBag Robotics Service Bus - rsb-0.18	Robotics Service RSBag Robotics Service		rsb-0.18	30%						·		•				
Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Support linked media files () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () bag record: Start timestamp for () Allow to deduplicate participants () Events with same timestamps are () Flush indices based on combined () show-progress online help doesn't ()	Robotics ServiceIn Progress 30%In Progress 50%New 0%In Progress 20%New 0%In Progress 40%New 0%In Progress 50%In Progress 60%New 0%New 0%New 0%New 0%In Progress 20%New 0%New 0%		rsb-0.18	30%												
Allow to specify output stream () Robotics Service Bus - rsb-1.0 Verify Elan backend Use data type definitions stored () Rename bag-merge -> bag-transform Support C++ as a client language	Robotics Service New 0% In Progress 30% In Progress 60% In Progress 50%	, , , ,	rsb-1.0	16%												
Support C++ as a client language Support Java as a client language Document C++ client API	New 0% New 0%															

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%