RSBag

		2024-12		2025-1			2025-2					2025-3				2025-4					2025-5					
	49				1_		3	4 5		6 7	7 8	3	9 10)	11	12 1	3	14	15	16	17	18	19	9 20	21	2
Robotics Service Bus			tics Se	rvic	ce Bu	3																				
RSBag		RSBa	'y tics Se		- D		0.4	0 000/																		
Robotics Service Bus - rsb-0.18						s -rsp	0.1	8 30%																		
Which timestamps should be set ()	In Progress 30% In Progress 50%																									
Newer tool versions should be able ()			-	50%	⁄o																					
Computation of channel format is ()		New (~~ ~	,																					
Extend Elan backend		New (ogress	20%	⁄o																					
Support proper temporal intervals ()				400	,																					
Support linked media files ()			ogress	40%	⁄o																					
Allow limiting recording time		New (-00	,																					
bag record: Make status output ()			ogress																							
Minimal support for ROSbag file ()			ogress	00%	⁄o																					
Support explicit backend selection		New (
Store start and end timestamp of ()		New (
bag record: Start timestamp for ()		New (New (
Allow to deduplicate participants ()																										
Bag as bus server crashes in case ()		New (~~ ~	,																					
Events with same timestamps are ()			ogress	20%	⁄o																					
Flush indices based on combined ()		New (
show-progress online help doesn't ()		New (New (
Allow to specify output stream ()			J‰ tics Se			, rah	1 0	160/																		
Robotics Service Bus - rsb-1.0				rvic	е ви	s -rsd	.1.0	10%																		
Verify Elan backend		New (~~ ~	,																					
Use data type definitions stored ()			ogress																							
Rename bag-merge -> bag-transform			ogress																							
Support C++ as a client language			ogress	50%	6																					
Support Java as a client language		New (
Document C++ client API		New (J%																							

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%