RSBag

	2024-2	2024-3			2024-4			2024-5				2024-6				2024-7			
		9 10		13	14 15	16 17	/ 18	3 19	20	21	22	23	24	25	26	27	28	29	30
Robotics Service Bus	Robotics Serv	ice Bus																	
RSBag	RSBag	D		000/															
Robotics Service Bus - rsb-0.18	Robotics Serv		-rsp-0.18	30%															
Which timestamps should be set ()	In Progress 30																		
Newer tool versions should be able ()	In Progress 50	1%																	
Computation of channel format is ()	New 0%	•																	
Extend Elan backend	In Progress 20	1%																	
Support proper temporal intervals ()	New 0%																		
Support linked media files ()	In Progress 40	1%																	
Allow limiting recording time	New 0%																		
bag record: Make status output ()	In Progress 50																		
Minimal support for ROSbag file ()	In Progress 60	1%																	
Support explicit backend selection	New 0%																		
Store start and end timestamp of ()	New 0%																		
bag record: Start timestamp for ()	New 0%																		
Allow to deduplicate participants ()	New 0%																		
Bag as bus server crashes in case ()	New 0%																		
Events with same timestamps are ()	In Progress 20	1%																	
Flush indices based on combined ()	New 0%																		
show-progress online help doesn't ()	New 0%																		
Allow to specify output stream ()	New 0%																		
Robotics Service Bus - rsb-1.0	Robotics Serv	ice Bus	s -rsb-1.0	16%															
Verify Elan backend	New 0%																		
Use data type definitions stored ()	In Progress 30																		
Rename bag-merge -> bag-transform	In Progress 60																		
Support C++ as a client language	In Progress 50	%																	
Support Java as a client language	New 0%																		
Document C++ client API	New 0%																		

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%