## RSBag

	2019-3		2019-4			2019-5				2019-6				2019-7				2019-8			
	10 11 12 13			17 1	8 -	19 2	0 21	22	23	24	25	26	27	28	29	30	31	32	33	34	35
Robotics Service Bus	Robotics Servic	e Bu	IS																		
RSBag	RSBag			0.000/																	
Robotics Service Bus - rsb-0.18	Robotics Servi		is -rsd-u.	18 30%																	
Which timestamps should be set ()	In Progress 309																				
Newer tool versions should be able ()	In Progress 509	6																			
Computation of channel format is ()	New 0%	,																			
Extend Elan backend	In Progress 209	6																			
Support proper temporal intervals ()	New 0%																				
Support linked media files ()	In Progress 409	6																			
Allow limiting recording time	New 0%																				
bag record: Make status output ()	In Progress 509																				
Minimal support for ROSbag file ()	In Progress 609	6																			
Support explicit backend selection	New 0%																				
Store start and end timestamp of ()	New 0%																				
bag record: Start timestamp for ()	New 0%																				
Allow to deduplicate participants ()	New 0%																				
Bag as bus server crashes in case ()	New 0%																				
Events with same timestamps are ()	In Progress 209	6																			
Flush indices based on combined ()	New 0%																				
show-progress online help doesn't ()	New 0%																				
Allow to specify output stream ()	New 0%																				
Robotics Service Bus - rsb-1.0	Robotics Servi	e Bu	is -rsb-1.	) 16%																	
Verify Elan backend	New 0%																				
Use data type definitions stored ()	In Progress 309																				
Rename bag-merge -> bag-transform	In Progress 609																				
Support C++ as a client language	In Progress 509	6																			
Support Java as a client language	New 0%																				
Document C++ client API	New 0%																				

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