RSBag

Robotics Service Bus RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Support linked media files () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined () Allow to specify output stream () Robotics Service Bus - rsb-1.0 Robotics Service Bus - rsb-0.18 30% In Progress 30% In Progress 50% New 0% In Progress 50% In Progress 50% In Progress 50% New 0% New		2020-3				2020-4			2020-5					2020-6				2020-7				2020-8				
RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to dedupticate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined () Allow to specify output stream () Robotics Service Bus -rsb-1.0 RSBag Robotics Service Bus -rsb-0.18 30% In Progress 30% In Progress 50% New 0% In Progress 40% New 0% In Progress 60% New 0%								16	17 18	3	19 20	21	22	23	2	24 25	26	27	28	29	30	31	32	33	34	35
Use data type definitions stored () Rename bag-merge -> bag-transform Support C++ as a client language In Progress 30% In Progress 60% In Progress 50%	RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () bag record: Start timestamp for () Allow to deduplicate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined () show-progress online help doesn't () Allow to specify output stream () Robotics Service Bus - rsb-1.0 Verify Elan backend Use data type definitions stored () Rename bag-merge -> bag-transform		11 Roboto RSBa Roboto RPro Rew C RPro Rew C Rew	12 1 tics Se g tics Se gress	rvid 309 509 409 609	ce Bi	15 us us -r	16	8 30%				222	23				27			-	31	32			35

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%

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