RSBag

	2020-3				2020-4				2020-5				2020-6				2020-7				2020-8			
	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35
Robotics Service Bus	**Robotics Service Bus**
RSBag	**RSBag**
Robotics Service Bus - rsb-0.18	**Robotics Service Bus -rsb-0.18 30%**
Which timestamps should be set (...)	**In Progress 30%**
Newer tool versions should be able (...)	**In Progress 50%**
Computation of channel format is (...)	**New 0%**
Extend Elan backend	**In Progress 20%**
Support proper temporal intervals (...)	**New 0%**
Support linked media files (...)	**In Progress 40%**
Allow limiting recording time	**New 0%**
bag record: Make status output (...)	**In Progress 50%**
Minimal support for ROSbag file (...)	**In Progress 60%**
Support explicit backend selection	**New 0%**
Store start and end timestamp of (...)	**New 0%**
bag record: Start timestamp for (...)	**New 0%**
Allow to deduplicate participants (...)	**New 0%**
Bag as bus server crashes in case (...)	**New 0%**
Events with same timestamps are (...)	**In Progress 20%**
Flush indices based on combined (...)	**New 0%**
show-progress online help doesn't (...)	**New 0%**
Allow to specify output stream (...)	**New 0%**
Robotics Service Bus - rsb-1.0	**Robotics Service Bus -rsb-1.0 16%**
Verify Elan backend	**New 0%**
Use data type definitions stored (...)	**In Progress 30%**
Rename bag-merge -> bag-transform	**In Progress 60%**
Support C++ as a client language	**In Progress 50%**
Support Java as a client language	**New 0%**
Document C++ client API	**New 0%**

Document Java client API	**New 0%**
Add TYPE block to TIDELog backend	**In Progress 20%**
Add META block to TIDELog backend	**In Progress 20%**