## RSBag

	2022-4		2022-5	2022-6 2022-7			2022-8				2022-9									
	14 15 16 17	-		21 2	2 23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38
Robotics Service Bus	Robotics Servio	ce Bus	S																	
RSBag	RSBag	-		<b>• •</b> ••																
Robotics Service Bus - rsb-0.18	Robotics Servi		s -rsb-0.1	8 30%																
Which timestamps should be set ()	In Progress 309																			
Newer tool versions should be able ()	In Progress 509	6																		
Computation of channel format is ()	New 0%																			
Extend Elan backend	In Progress 209	6																		
Support proper temporal intervals ()	New 0%																			
Support linked media files ()	In Progress 409	6																		
Allow limiting recording time	New 0%																			
bag record: Make status output ()	In Progress 50%																			
Minimal support for ROSbag file ()	In Progress 609	6																		
Support explicit backend selection	New 0%																			
Store start and end timestamp of ()	New 0%																			
bag record: Start timestamp for ()	New 0%																			
Allow to deduplicate participants ()	New 0%																			
Bag as bus server crashes in case ()	New 0%																			
Events with same timestamps are ()	In Progress 209	6																		
Flush indices based on combined ()	New 0%																			
show-progress online help doesn't ()	New 0%																			
Allow to specify output stream ()	New 0%																			
Robotics Service Bus - rsb-1.0	Robotics Servi	ce Bus	s -rsb-1.0	16%																
Verify Elan backend	New 0%																			
Use data type definitions stored ()	In Progress 309	6																		
Rename bag-merge -> bag-transform	In Progress 609	6																		
Support C++ as a client language	In Progress 509	6																		
Support Java as a client language	New 0%																			
Document C++ client API	New 0%																			

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%