## RSBag

	2023-5		2023-6			20	23-7		2023-8				2023-9				2023-10			
	18 19 20		22 23	24 25	26	27 28	29	30 3	31	32 33	34	35	36	37 3	8	39	40	41	42	43
Robotics Service Bus	Robotics	s Servi	ce Bus		•		•	•												
RSBag	RSBag				<b>00</b> 0/															
Robotics Service Bus - rsb-0.18	Robotics			rsd-0.18	30%															
Which timestamps should be set ()	In Progr																			
Newer tool versions should be able ()	In Progr		%																	
Computation of channel format is ()	New 0%		N																	
Extend Elan backend	In Progr New 0%		/o																	
Support proper temporal intervals ()			N/																	
Support linked media files ()	In Progr		/o																	
Allow limiting recording time	New 0%		<b>N</b> /																	
bag record: Make status output ()	In Progr																			
Minimal support for ROSbag file ()	In Progr New 0%		/o																	
Support explicit backend selection	New 0%																			
Store start and end timestamp of ()	New 0%																			
bag record: Start timestamp for ()	New 0%																			
Allow to deduplicate participants ()	New 0%																			
Bag as bus server crashes in case ()	In Progr		D/.																	
Events with same timestamps are ()	New 0%		/0																	
Flush indices based on combined ()	New 0%																			
show-progress online help doesn't ()	New 0%																			
Allow to specify output stream ()	Robotics		co Rue -	reh_1 0 1	<b>6%</b>															
Robotics Service Bus - rsb-1.0	New 0%		ce bus -	150-1.0 1	0 /0															
Verify Elan backend	In Progr		D/.																	
Use data type definitions stored ()	In Progra																			
Rename bag-merge -> bag-transform	In Progr																			
Support C++ as a client language	New 0%		/0																	
Support Java as a client language	New 0%																			
Document C++ client API		•																		

/ 0%
rogress 20%
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