RSBag

	2021-6	2021-7			2021-8			2021-9				2021-10				2021-11			
		26 27	28 29	30	31 32	33 3	84 35	36	37	38	39	40	41 42	2 43	44	45	46	47	
Robotics Service Bus	Robotics Servi	ce Bus		•					•					•	•	•	•		
RSBag	RSBag			00 0/															
Robotics Service Bus - rsb-0.18	Robotics Servi		rsb-0.18	30%															
Which timestamps should be set ()	In Progress 30°																		
Newer tool versions should be able ()	In Progress 50°	%																	
Computation of channel format is ()	New 0%																		
Extend Elan backend	In Progress 20°	%																	
Support proper temporal intervals ()	New 0%																		
Support linked media files ()	In Progress 40°	%																	
Allow limiting recording time	New 0%																		
bag record: Make status output ()	In Progress 50°																		
Minimal support for ROSbag file ()	In Progress 60°	%																	
Support explicit backend selection	New 0%																		
Store start and end timestamp of ()	New 0%																		
bag record: Start timestamp for ()	New 0%																		
Allow to deduplicate participants ()	New 0%																		
Bag as bus server crashes in case ()	New 0%																		
Events with same timestamps are ()	In Progress 20°	%																	
Flush indices based on combined ()	New 0%																		
show-progress online help doesn't ()	New 0%																		
Allow to specify output stream ()	New 0%																		
Robotics Service Bus - rsb-1.0	Robotics Servi	ce Bus -	rsb-1.0 1	6%															
Verify Elan backend	New 0%																		
Use data type definitions stored ()	In Progress 30 ^o	%																	
Rename bag-merge -> bag-transform	In Progress 60 ^o																		
Support C++ as a client language	In Progress 50°	%																	
Support Java as a client language	New 0%																		
Document C++ client API	New 0%																		

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%