## RSBag

Robotics Service Bus RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () Bag as bus server crashes in case ()  ROBOTICS Service Bus RSBag Robotics Service Bus - rsb-0.18 30% In Progress 30% In Progress 50% New 0% In Progress 50% New 0% In Progress 50% New 0%
RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () RSBag Robotics Service Bus -rsb-0.18 30% In Progress 30% In Progress 50% New 0% In Progress 50% In Progress 40% New 0% In Progress 50% In Progress 50% In Progress 50% In Progress 50% New 0%
Events with same timestamps are ()  Flush indices based on combined ()  show-progress online help doesn't ()  Allow to specify output stream ()  Robotics Service Bus - rsb-1.0  Verify Elan backend  Use data type definitions stored ()  Possers has marge as has transform  In Progress 20%  New 0%  New 0%  Robotics Service Bus -rsb-1.0 16%  New 0%  In Progress 30%  In Progress 30%  In Progress 60%

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add TTPE block to TibeLog backerid	In Progress 209/
Add META block to TIDELog backend	In Progress 20%

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