RSBag

	2019-7	2019-7 2019-8		2019-9			2019-10				2	2019-11		2019-12				
		31 32	33 34	35	36 37	38	39	40	41 42	43	44	45	46 4	7 48	49	50	51	52
Robotics Service Bus	Robotics Service	e Bus																
RSBag	RSBag			000/														
Robotics Service Bus - rsb-0.18	Robotics Service		rsb-0.18	30%														
Which timestamps should be set ()	In Progress 30%																	
Newer tool versions should be able ()	In Progress 50%	6																
Computation of channel format is ()	New 0%	,																
Extend Elan backend	In Progress 20%	6																
Support proper temporal intervals ()	New 0%																	
Support linked media files ()	In Progress 40%	6																
Allow limiting recording time	New 0%																	
bag record: Make status output ()	In Progress 50%																	
Minimal support for ROSbag file ()	In Progress 60%	6																
Support explicit backend selection	New 0%																	
Store start and end timestamp of ()	New 0%																	
bag record: Start timestamp for ()	New 0%																	
Allow to deduplicate participants ()	New 0%																	
Bag as bus server crashes in case ()	New 0%																	
Events with same timestamps are ()	In Progress 20%	6																
Flush indices based on combined ()	New 0%																	
show-progress online help doesn't ()	New 0%																	
Allow to specify output stream ()	New 0%																	
Robotics Service Bus - rsb-1.0	Robotics Service	e Bus -	rsb-1.0	16%														
Verify Elan backend	New 0%																	
Use data type definitions stored ()	In Progress 30%																	
Rename bag-merge -> bag-transform	In Progress 60%																	
Support C++ as a client language	In Progress 50%	6																
Support Java as a client language	New 0%																	
Document C++ client API	New 0%																	

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add TTPE block to TibeLog backetid	In Progress 209/
Add META block to TIDELog backend	In Progress 20%

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