## RSBag

Robotics Service Bus  RSBag  Robotics Service Bus - rsb-0.18  Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined () Allow to specify output stream () Allow to specify output stream () Robotics Service Bus - rsb-1.0 16%
RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Allow limiting recording time bag record: Make status output () Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () Allow to deduplicate participants () Bag as bus server crashes in case () Flush indices based on combined () Allow to specify output stream () Robotics Service Bus - rsb-0.18 30% In Progress 30% In Progress 50% New 0% New 0% In Progress 50% In Progress 50% In Progress 60% New 0% Robotics Service Bus - rsb-1.0 16%
Verify Elan backend  Use data type definitions stored ()  Rename bag-merge -> bag-transform  New 0%  In Progress 30%  In Progress 60%

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Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
1	In Progress 20%
Add META block to TIDELog backend	iii i logiess 20 %

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