RSBag

	2022-7		2022-8			2022-9			2022-10				2022-11					2022-12				
		29 30		32 33	34 3	5	36 3	7 38	39	40	41	42	43	44	45	46	47	48	49	50	51	5
Robotics Service Bus		tics Servio	e Bu	S																		
RSBag	RSBa	-																				
Robotics Service Bus - rsb-0.18		ics Servi		s -rsb-0.	18 30%																	
Which timestamps should be set ()		gress 309																				
Newer tool versions should be able ()		gress 50%	6																			
Computation of channel format is ()	New 0		,																			
Extend Elan backend		gress 20%	6																			
Support proper temporal intervals ()	New 0																					
Support linked media files ()		gress 409	6																			
Allow limiting recording time	New 0	, -																				
bag record: Make status output ()		gress 50%																				
Minimal support for ROSbag file ()		gress 609	6																			
Support explicit backend selection	New 0																					
Store start and end timestamp of ()	New 0																					
bag record: Start timestamp for ()	New 0																					
Allow to deduplicate participants ()	New 0																					
Bag as bus server crashes in case ()	New 0																					
Events with same timestamps are ()		gress 209	6																			
Flush indices based on combined ()	New 0																					
show-progress online help doesn't ()	New 0	, -																				
Allow to specify output stream ()	New 0		_																			
Robotics Service Bus - rsb-1.0		tics Servio	e Bu	s -rsb-1.) 16%																	
Verify Elan backend	New 0																					
Use data type definitions stored ()		gress 309																				
Rename bag-merge -> bag-transform		gress 60%																				
Support C++ as a client language		gress 50%	6																			
Support Java as a client language	New 0																					
Document C++ client API	New 0	1%																				

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%