RSBag

		2024-7			2024-8				2024-9				2024-10				2024-11				2024-12				
	27	28		30			33 3	4 35	3	6 37	38	3	9 40	41	42	43	44	45	46	47	48	49	50	51	52
Robotics Service Bus RSBag Robotics Service Bus - rsb-0.18 Which timestamps should be set () Newer tool versions should be able () Computation of channel format is () Extend Elan backend Support proper temporal intervals () Support linked media files () Allow limiting recording time bag record: Make status output ()		28 Robo RSB Robo In Pr New In Pr New In Pr	29 otics S ogres: ogres: 0% ogres: 0% ogres:	ervi s 30 s 50 s 20 s 40	ice Bus % % %	2	33 3		-1		-		9 40	-	-	-	44		-	-	48	49	-		
Minimal support for ROSbag file () Support explicit backend selection Store start and end timestamp of () bag record: Start timestamp for () Allow to deduplicate participants () Bag as bus server crashes in case () Events with same timestamps are () Flush indices based on combined ()		In Pr New New New New New In Pr	ogres: 0% 0% 0% 0% 0% ogres: 0%	s 60	%																				
show-progress online help doesn't () Allow to specify output stream () Robotics Service Bus - rsb-1.0 Verify Elan backend Use data type definitions stored () Rename bag-merge -> bag-transform Support C++ as a client language Support Java as a client language Document C++ client API		New In Pr In Pr	0% otics S 0% ogress ogress ogress 0%	s 30 s 60	%	-rs	sb-1.0	16%																	

Document Java client API	New 0%
Add TYPE block to TIDELog backend	In Progress 20%
Add META block to TIDELog backend	In Progress 20%