

Robotics Systems Types - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|---------|--------|----------|---|----------|---------------------|----------|--------|
| 842 | Tasks | New | Normal | Extract Joint Mapping Information from JointState.proto into Seperate BodySchema Representation | | 12/17/2015 09:19 AM | protocol | 0 |